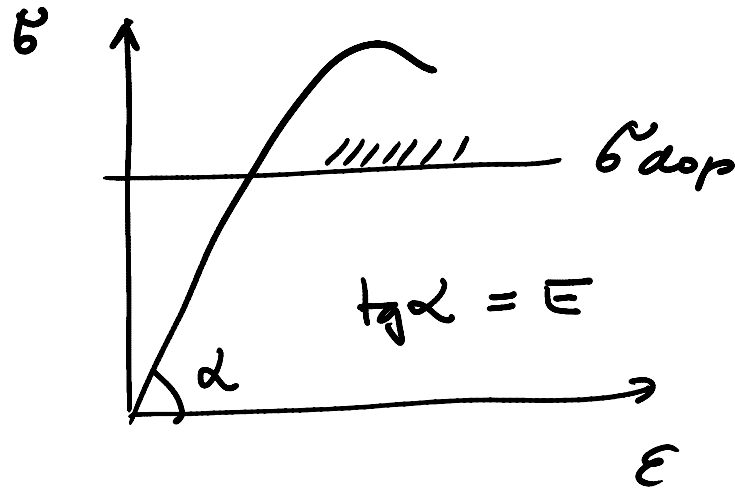


$$\sigma = \frac{F}{A}$$

$$\epsilon = \frac{f}{l}$$

U ZMETI



$$\sigma = E \cdot \epsilon$$

$$\frac{F}{A} = E \frac{f}{l}$$

σ PODAJNOST

$$f = \frac{l}{AE} F$$

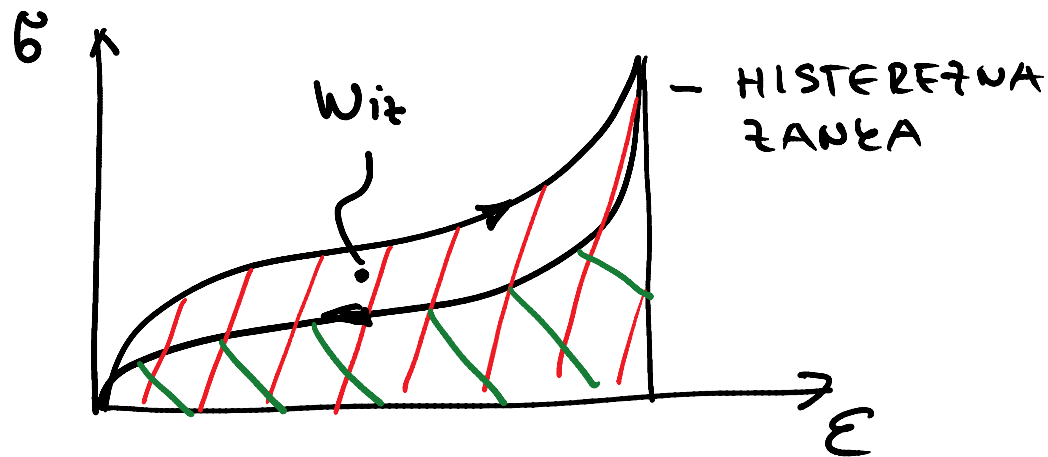
f DEFORMACIJA

$$f = \sigma F$$

VELIKO PODAJNOST DOSEŽEMO + OBLIKOVANJEM UTMETI
 OŠIROKA + UPORABO MATERIALU + NIŽIM ϵ

JEZLENE UTMETI

GUMIJASTE UTMETI



 W_{do}

 W_{od}

$$\eta = \frac{W_{od}}{W_{do}}$$

IZORISTEK

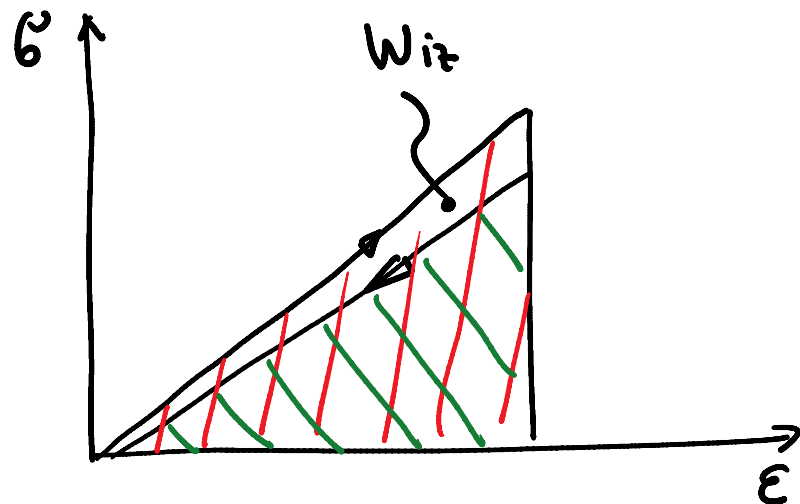
$$W_{do} = W_{od} + W_{iz}$$

$W_{iz} \uparrow$

GUMIJASTA UTMET
 HIPERELASTIČNA

$$W_{iz} \rightarrow Q \rightarrow T \uparrow \quad T \leq T_{dop}$$

IHAJO NIŽEK η ZATO DOBRO DUŠIJO VIBRACIJE
 JEYIENA U+MET



 W_{as}
 W_{od}

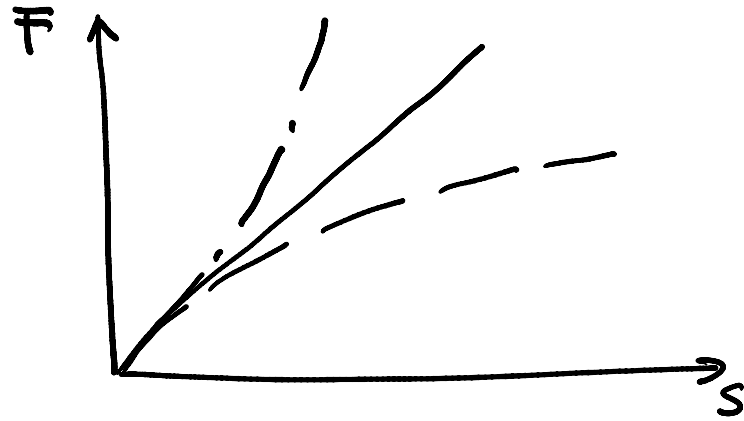
$W_{itz} \downarrow$ $\eta \uparrow$
 SLABO DUŠIJO VIBRACIJE



LISTNATA U+MET

$\eta \downarrow$ DOBRO DUŠI
 VIBRACIJE

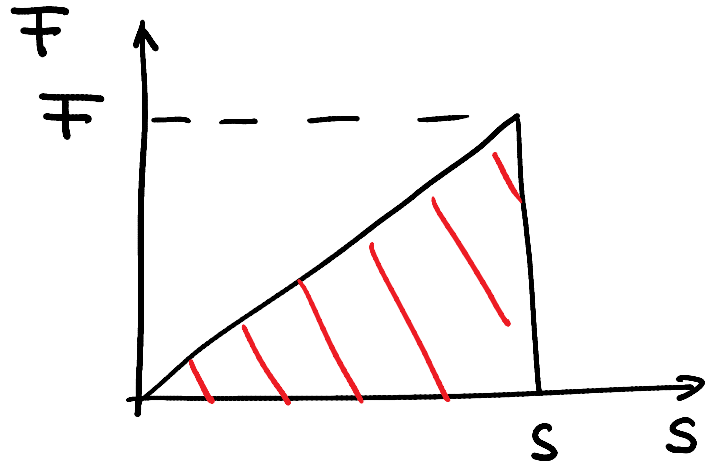
ΧΑΡΑΚΤΗΡΙΣΤΙΚΑ ΥΓΜΕΤΙ



- .- PROGRESIUNA
- LINEARNA
- .- DEGRESIUNA

S ΠΟΥΕΣ ΥΓΜΕΤΙ

VOLUMSKI IZKORISTEK

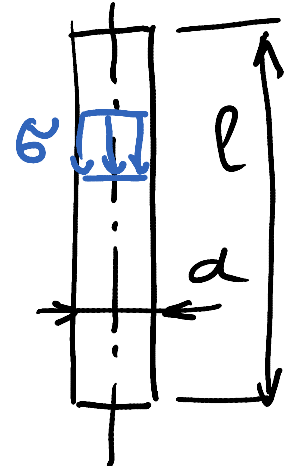


$$W_{do} = \frac{F \cdot s}{2}$$

$$\sigma = \frac{F}{A}$$

$$\epsilon = \frac{s}{l}$$

$$\sigma = E \cdot \epsilon$$



$$W_{do} = \frac{\sigma A \epsilon \cdot l}{2} = \frac{\sigma V \epsilon}{2E} = \frac{\sigma^2 V}{2E}$$

$$A = \frac{\pi d^2}{4}$$

$$W_{max} = \frac{\sigma_{max}^2 \cdot V}{2E} = W_{do}$$

$$V = A \cdot l$$

$$\sigma = \sigma_{max}$$

$$W = \frac{1}{2E} \int_V \sigma^2 dV$$

$$\eta_v = \frac{W}{W_{max}}$$

$$\eta_v = 1$$

$$W_{\max} = \frac{\tau_{\max}^2 V}{2G}$$



ZA STRIŽNE
UŽMETI

$$W = \frac{1}{2G} \int_V \tau^2 dV$$



$$W_{\max} = \frac{\sigma_{\max}^2 U}{2E}$$



ZA UPOGIBNE
UŽMETI

$$W = \frac{1}{2E} \int_V \sigma^2 dV$$



$$\eta_v = \frac{W}{W_{\max}}$$

VRSTE UŽMETI

UPOGIBNE Δ X

UŽVOJNE Δ X

TLAČNE X

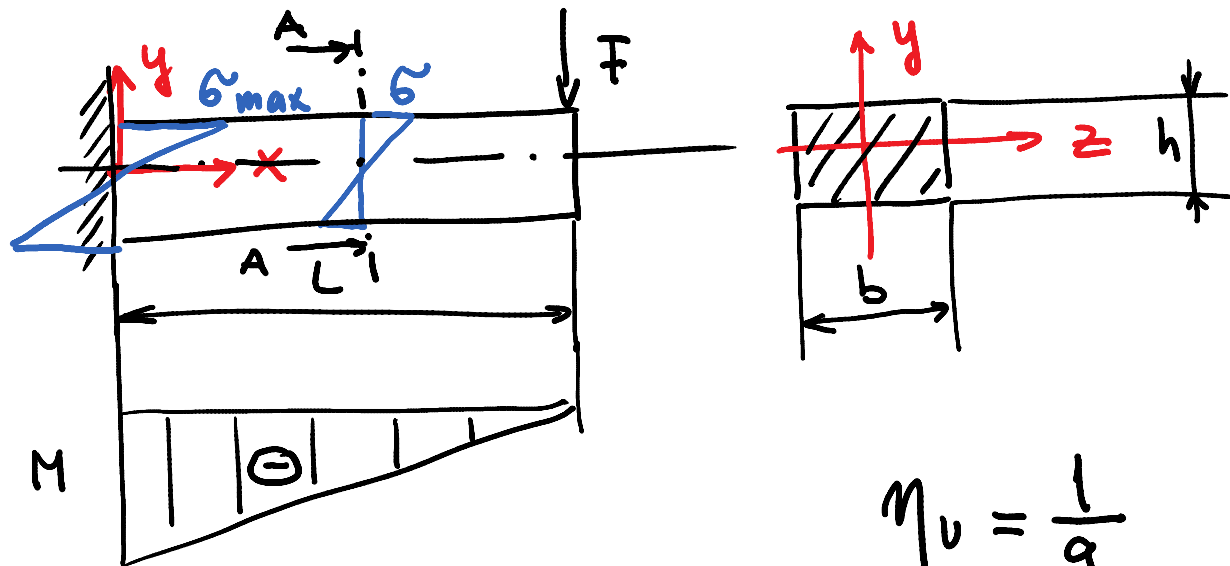
STRIŽNE X

MEMBRANSKE Δ

Δ ŽOUINSKE

X POLIMERNE

UPOGIBNA KONTROLNA UZMET



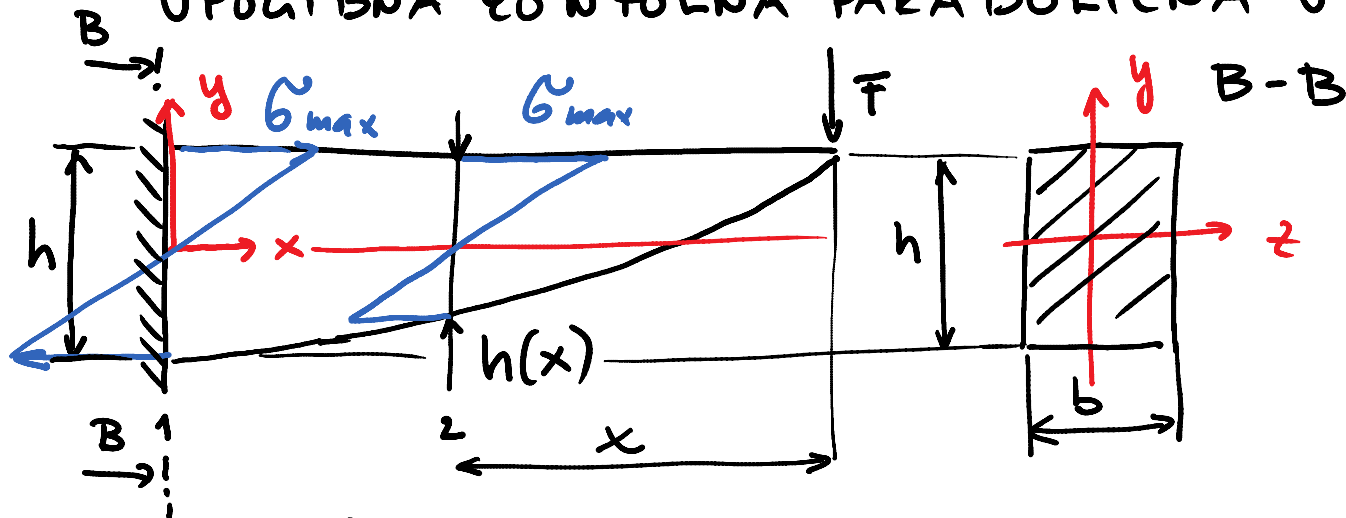
$$\eta_v = \frac{l}{9}$$

Free body diagram of a beam segment of length x . The forces shown are a downward force F at the right end, a counter-clockwise moment $M(x)$ at the left end, and a shear force $T(x)$ acting downwards at the left end.

$$M(x) = -F \cdot x$$

$$T(x) = -F$$

UPOGIBNA KONTROLNA PARABOLIČNA UŽMET



$$\eta_v = \frac{1}{3}$$

$$G_{max} = \frac{F \cdot L}{W_z} = \frac{F \cdot L \cancel{G}}{b h^2} = \frac{F \cdot x \cancel{G}}{b h(x)^2}$$

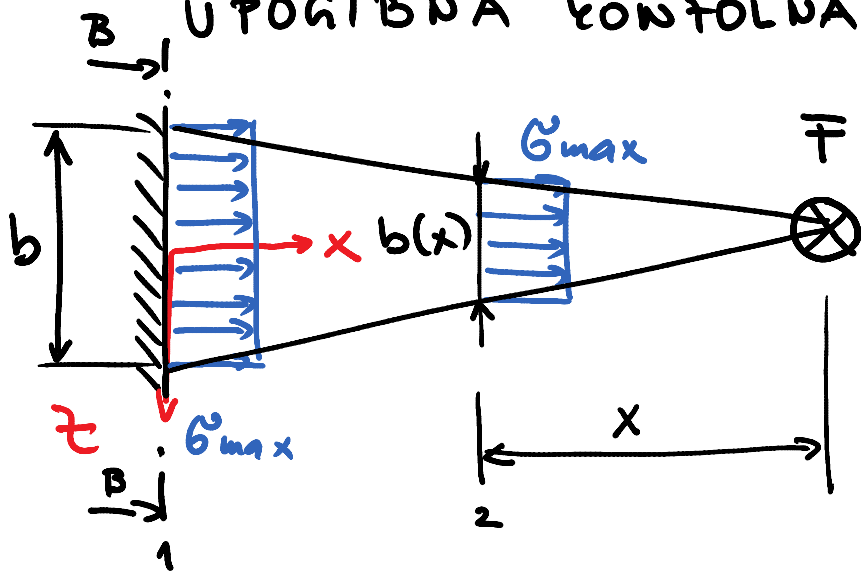
$$W_z = \frac{b \cdot h^2}{6}$$

$$\frac{L}{h^2} = \frac{x}{h(x)^2}$$

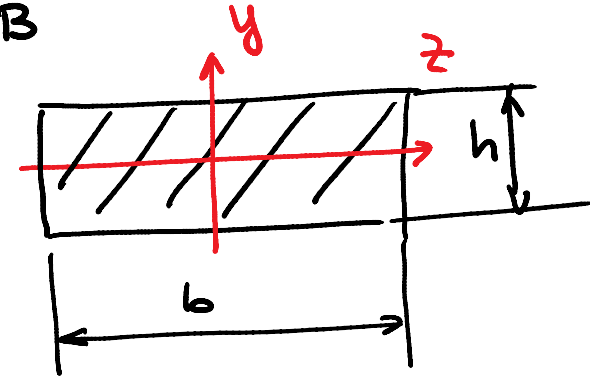
$$h(x)^2 = \frac{x}{L} h^2$$

$$h(x) = \sqrt{\frac{x}{L}} h$$

UPOGIBNA KONTROLNA TRIKOTNA UZMET



B-B



$$\sigma_{max} = \frac{q \cdot L}{b h^2} = \frac{q \cdot x}{b(x) h^2}$$

$$\frac{L}{b} = \frac{x}{b(x)}$$

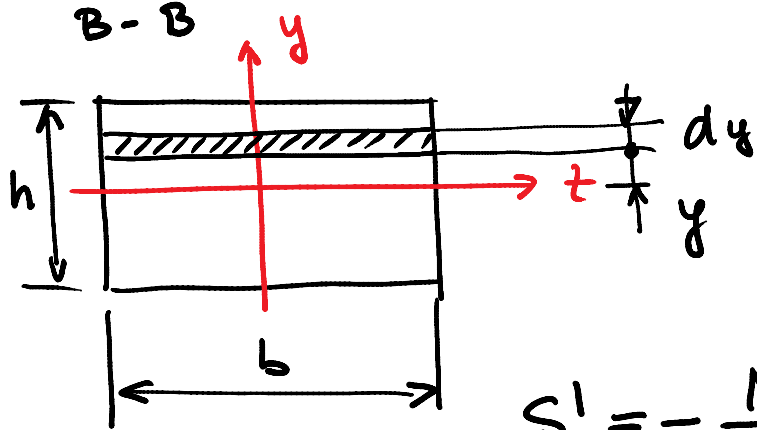
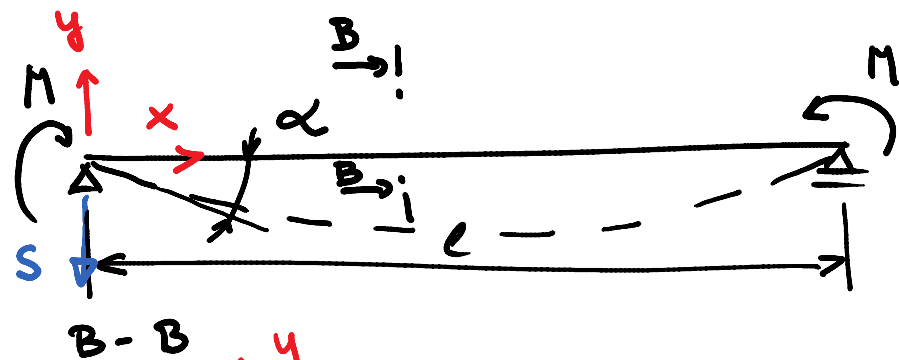
$$b(x) = \frac{x}{L} b$$

$$\eta_v = \frac{1}{3}$$

LISTNATA UPOGIBNA UZMET

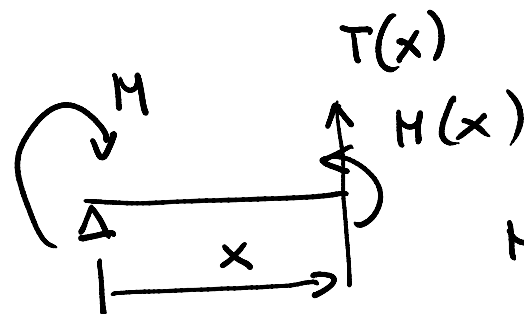
$\eta_v \approx \frac{1}{3}$ GLEJ SLIKOVNO GRADIVO

UPOGIBNA SPIRALNA VITMET



$$M = F \cdot r_a$$

$$\varphi = 2 \cdot \alpha$$



$$H(x) = M$$

$$S'' = - \frac{M(x)}{EI_z}$$

$$S' = - \frac{M}{EI_z} x + C_1$$

$$S = - \frac{M}{EI_z} x^2 \frac{1}{2} + C_1 x + C_2$$

$$C_2 = 0$$

R.P.

$$x = 0 ; S = 0$$

$$x = l ; S = 0$$

$$\theta = -\frac{M}{EI_2} \frac{l^2}{2} + C_1 \cdot l \quad C_1 = \frac{Ml}{2EI_2}$$

$$s'(x=0) = \operatorname{tg} \alpha \approx \alpha = C_1$$

$$s' = \frac{ds}{dx} = \operatorname{tg} \alpha$$

$$\alpha = \frac{l \cdot M}{2EI_2}$$

$$2\alpha = \varphi \\ M = F \cdot r_a$$

$$\frac{\varphi}{2} = \frac{l r_a}{2EI_2} F$$

$$\varphi = \frac{l \cdot r_a}{EI_2} F$$

$\sigma =$

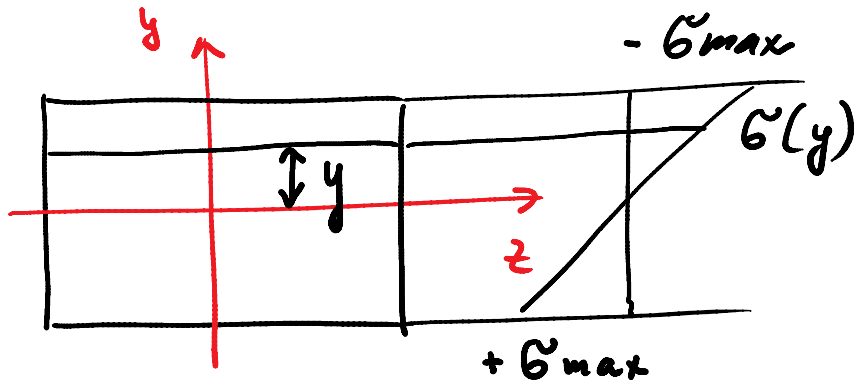
$$W_{\max} = \frac{\sigma_{\max}^2 V}{2E}$$

$$\sigma_{\max} = \frac{M}{W_z} = \frac{M}{I_z} \frac{h}{2} \quad ; \quad W_z = \frac{b \cdot h^2}{6}$$

$$W_{\max} = \frac{M^2 V h^2}{I_z^2 8E}$$

$$dV = b dy l \quad ; \quad \sigma(y) = \frac{M}{I_z} y$$

$$W = \frac{1}{2E} \int_V \sigma^2 dV = \frac{b l M^2}{2E I_z^2} \int_{-\frac{h}{2}}^{\frac{h}{2}} y^2 dy = \frac{b l M^2}{2E I_z^2} \frac{1}{3} \left(\frac{h^3}{8} + \frac{h^3}{8} \right)$$



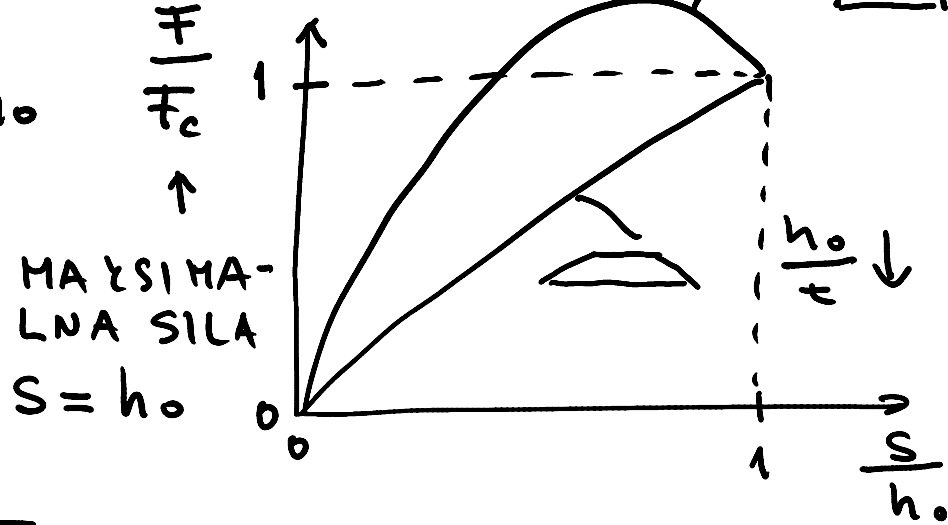
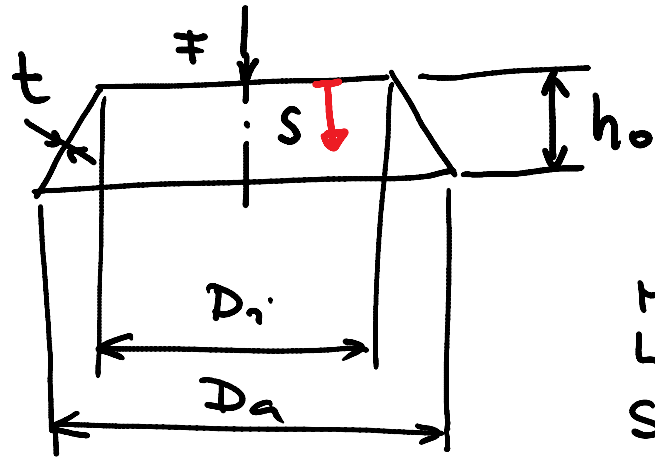
$$W = \frac{b l M^2 h^3}{24 E I_z^2}$$

$$W = \frac{M^2 V h^2}{I_z^2 24 E}$$

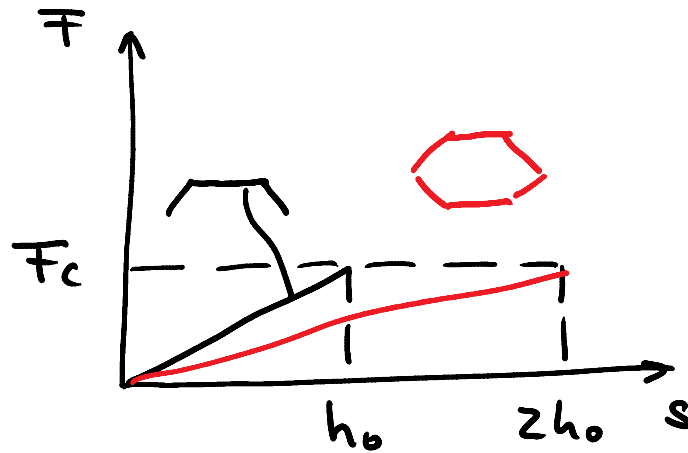
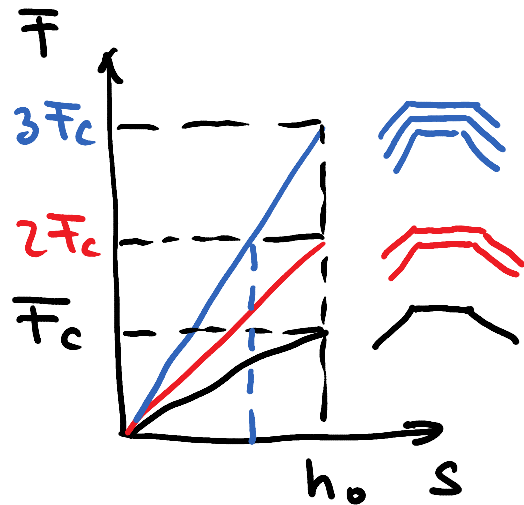
$$V = b l h$$

$$\eta_V = \frac{W}{W_{\max}} = \frac{8}{24} = \frac{1}{3}$$

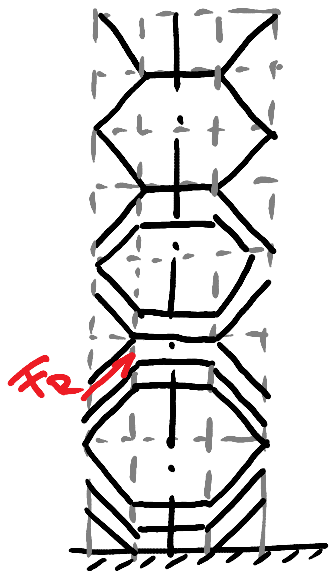
MEMBRANSKA VŮHMET



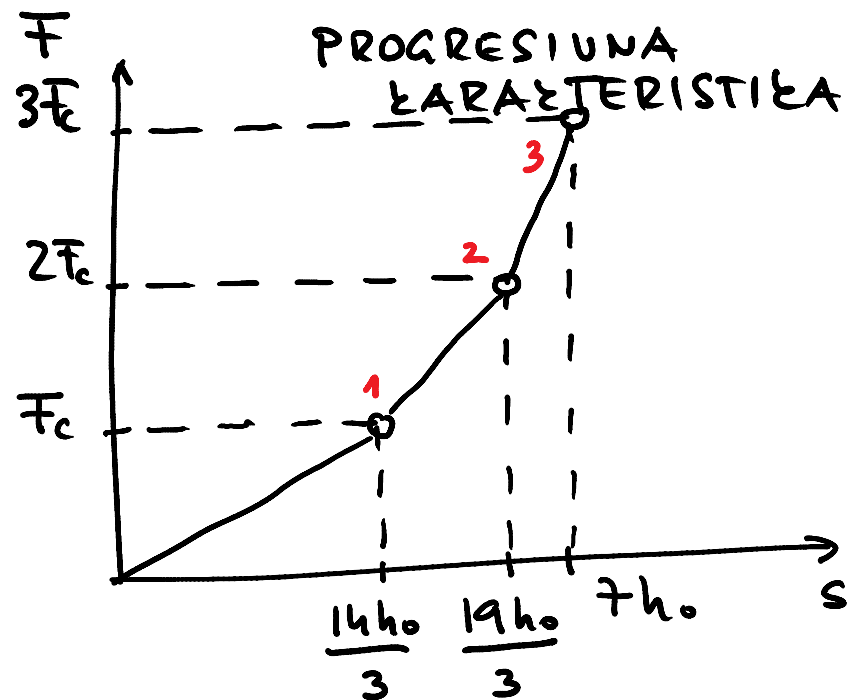
$\frac{h_0}{t} \uparrow$



PREDPOSTAVIMO,
 DA JE
 ZARÁTERISTIKA
 LINEÁRNA

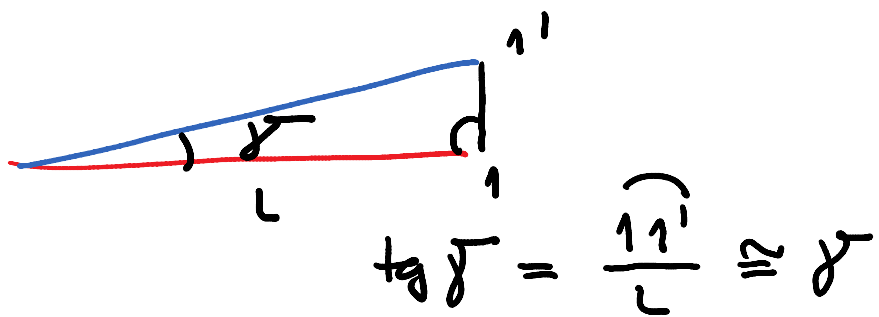
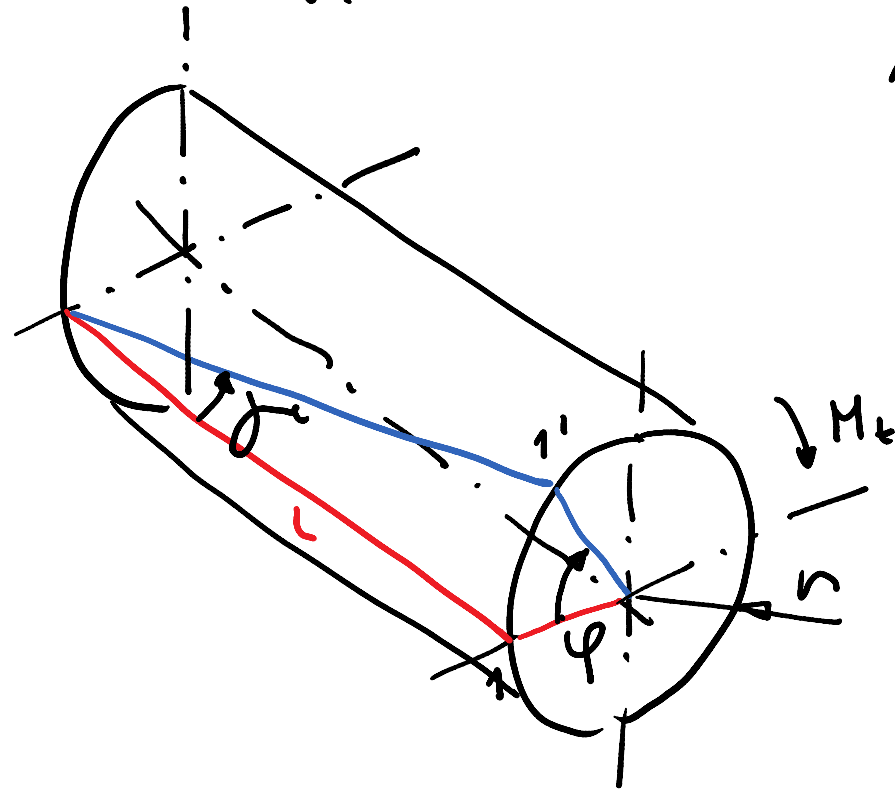


1	F_c	2	$2F_c$	3	$3F_c$
	h_0		h_0		h_0
	h_0		h_0		h_0
	h_0		h_0		h_0
	h_0		h_0		h_0
	$\frac{1}{2} h_0$		h_0		h_0
	$\frac{1}{2} h_0$		h_0		h_0
	$\frac{1}{3} h_0$		$\frac{2}{3} h_0$		h_0
	$\frac{1}{3} h_0$		$\frac{2}{3} h_0$		h_0
	$\frac{1}{3} h_0$		$\frac{2}{3} h_0$		h_0
	$\frac{1}{3} h_0$		$\frac{2}{3} h_0$		h_0
	$\frac{14 h_0}{3}$		$\frac{19 h_0}{3}$		$\frac{21 h_0}{3}$



DOBRO DUŠIJO VIBRACIJE

VAZUOJNA PALIČNA VRTMET



$$\Delta l = r \cdot \varphi \approx l \cdot \gamma$$

$$\sigma = G \cdot \gamma$$

$$\sigma = \frac{M_t}{W_{po}} ; \gamma = r \varphi \frac{1}{l}$$

$$\frac{M_t}{W_{po}} = G \frac{r}{l} \varphi$$

$$\varphi = \frac{l M_t}{W_{po} r \cdot G}$$

$$\varphi = \frac{l}{I_{po} G} M_t$$

$$W_{\max} = \frac{\tau_{\max}^2 \cdot V}{2G}$$

$$W_{\max} = \frac{M_t^2 r^2 V}{I_{po}^2 2G}$$

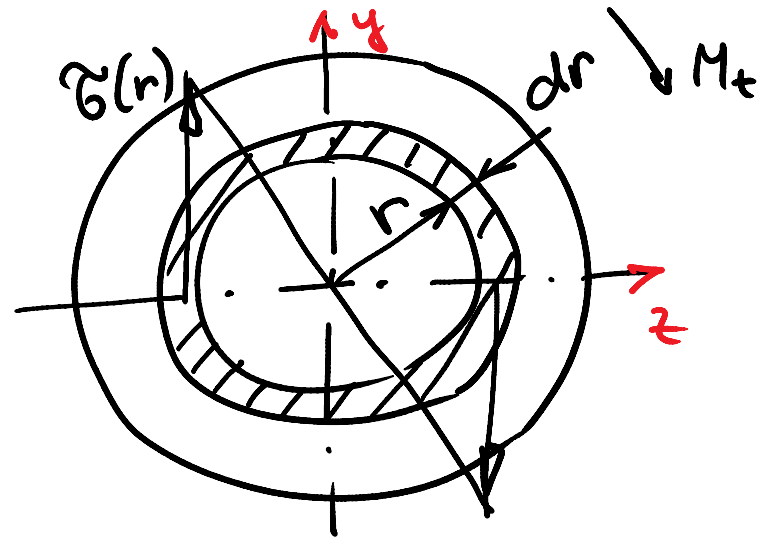
$$W = \frac{1}{2G} \int \tau^2 dV$$

$$= \frac{1}{2G} \frac{M_t^2 2\bar{r}l}{I_{po}^2} \int_0^r r^3 dr$$

$$= \frac{M_t^2 \bar{r} l}{G I_{po}^2} \frac{r^4}{4}$$

$$= \frac{M_t^2 r^2 V}{I_{po}^2 4G}$$

$$\tau_{\max} = \frac{M_t}{W_{po}} = \frac{M_t r}{I_{po}}$$

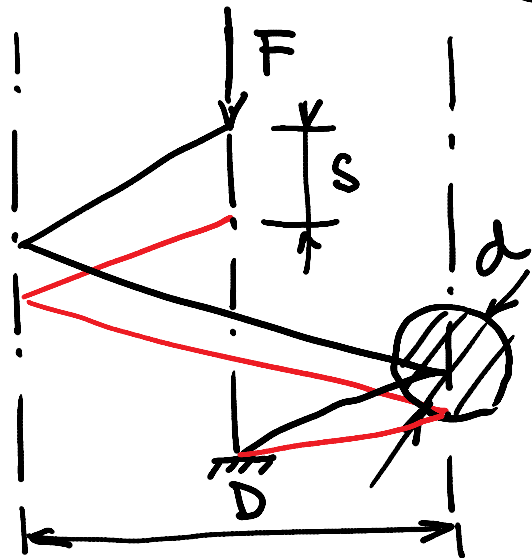
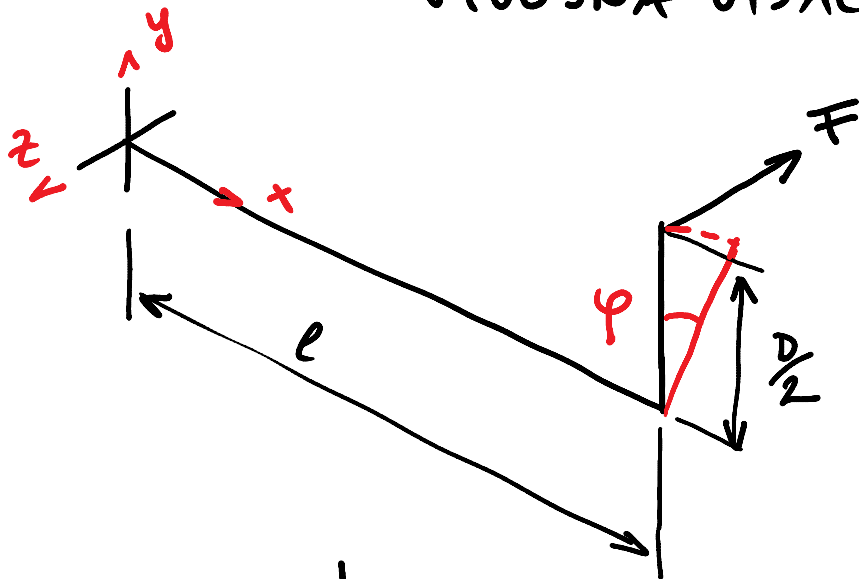


$$dV = 2\bar{r} r dr l$$

$$\tau(r) = \frac{M_t}{I_{po}} r$$

$$\eta_v = \frac{2}{4} = \frac{1}{2}$$

VRUČNA VIJAČNA VŹMET



$$l = \pi D n$$

n - ŠTEVILO EFEKTIVNIH
NAVOJEU VŹMETI

$$M_t = F \cdot \frac{D}{2}$$

$$s = \varphi \cdot \frac{D}{2}$$

$$\varphi = \frac{l}{I_{p0} G} M_t$$

$$\frac{2s}{D} = \frac{\pi D n}{I_{p0} G} \frac{D}{2} F$$

$$s = \frac{\pi D^3 n}{4 I_{p0} G} F$$

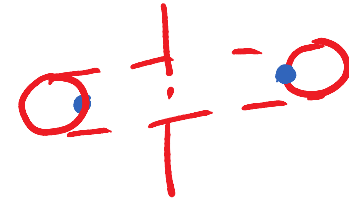
$$\eta_v = \frac{1}{2}$$

$$n_t = n + 2 \quad \text{HLADNO PŘEOBLIKOVANÁ UŽMET}$$

$$n_t = n + 1,5 \quad \text{TOPLO PŘEOBLIKOVANÁ UŽMET}$$

$$n_t = 3,5, 4,5, 5,5, \dots$$

VREDNOTENJE UZROJNE VIJAČNE VRTETI
NA STATIČNO NOSILNOST



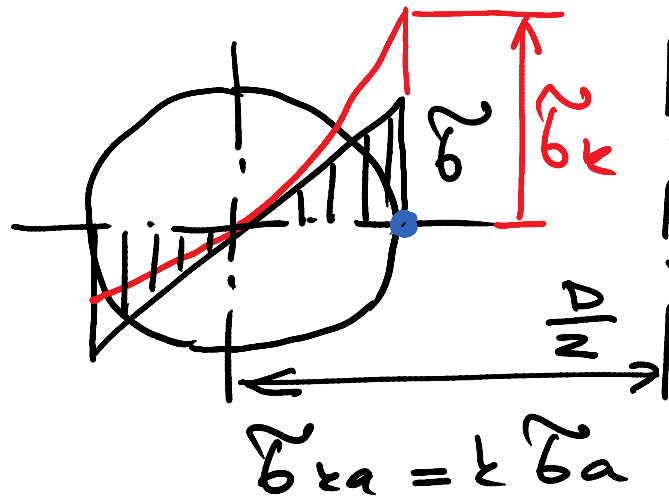
$$\sigma = \frac{M_t}{W_{p0}} \leq \sigma_{dop} \quad \leftarrow \quad \sigma = \sigma_{max}$$

$$\sigma_c = \frac{M_{tc}}{W_{p0}} \leq \sigma_{cdop}$$

C - BLOKIRANA DOLŽINA
VRTETI

$$M_{tc} = \frac{F_c \cdot D}{2}$$

DINAMIČNA NOSILNOST



$$\sigma_k = k \sigma$$

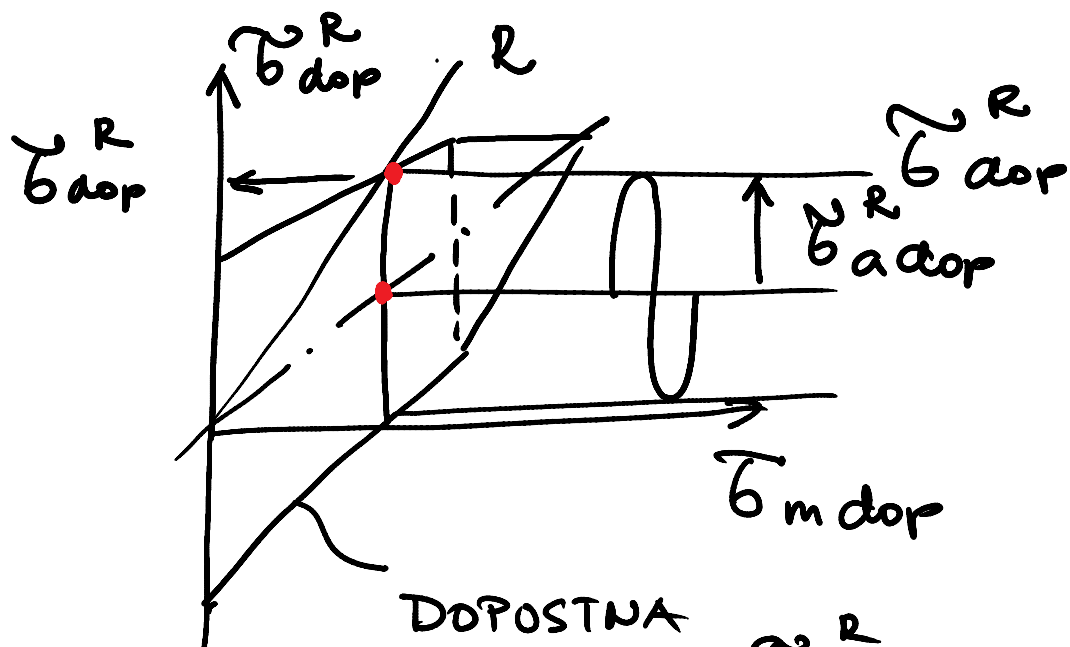
UPOŠTEVA KONCENTRACIJO

NA PETOSTI ŽARADI

UVRUČENOSTI ŽICE

$$\sigma_k \leq \sigma_{dop}^R$$

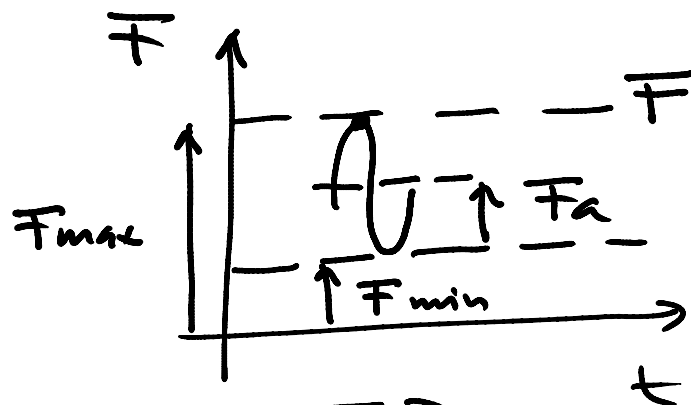
$$\sigma_{ka} \leq \sigma_{da}^R$$



DOPOSTNA
NAPETOST σ_{dop}^R

$$\sigma_{dop}^R = \frac{\sigma_{obl}^R \cdot b_1 \cdot b_2}{\beta \cdot \epsilon \cdot \gamma}$$

$$M_t = \frac{F \cdot D}{2}$$

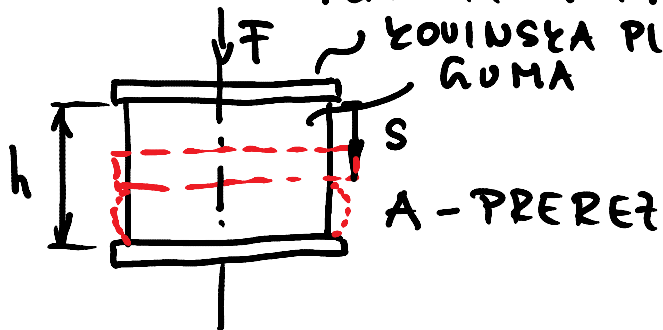


$$\sigma = \frac{F \cdot D}{2 W_p}$$

$$\sigma_a = \frac{F_a \cdot D}{2 W_p}$$

$$R = \frac{\sigma_{min}}{\sigma_{max}} = \frac{F_{min}}{F_{max}}$$

TLAČNA GUMIJASTA VŤMET



$$\sigma = E \cdot \epsilon$$

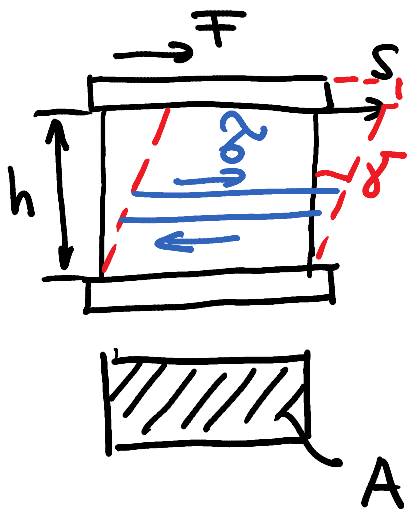
$$\frac{F}{A} = E \frac{s}{h} \rightarrow s = \frac{h}{AE} F$$

$$\sigma_{max} = \frac{F}{A}$$

$$\eta_v = 1$$

$$s = \frac{h}{AE} F$$

ΣΤΡΙΪΝΑ ΠΡΕΤΜΑΤΙΪΝΑ ΓΥΜΙΪΑΣΤΑ VŤMET



$$\tau = G \cdot \gamma$$

$$\tan \gamma = \frac{s}{h} \approx \gamma$$

$$\tau = \frac{F}{A}$$

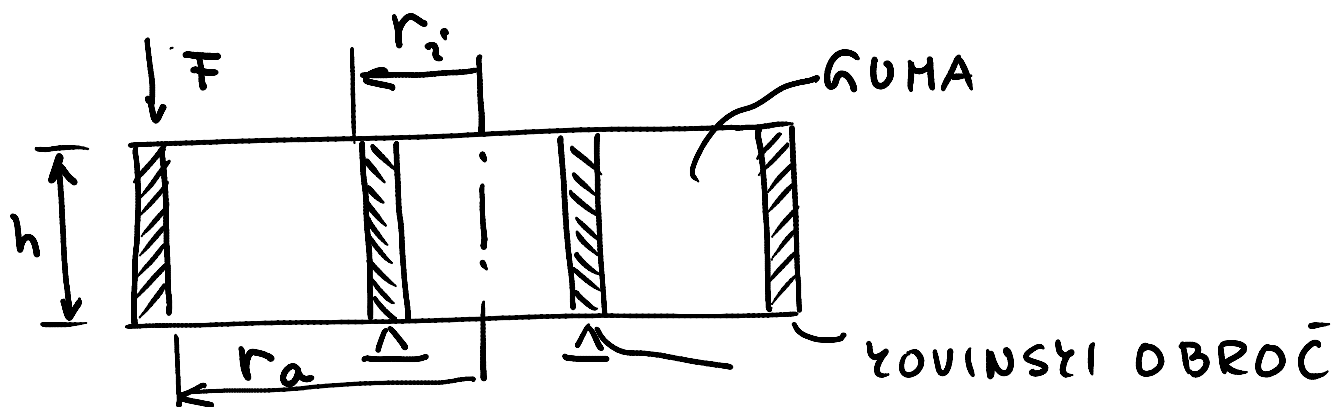
$$\frac{F}{A} = G \cdot \frac{s}{h}$$

$$s = \frac{h}{AG} F$$

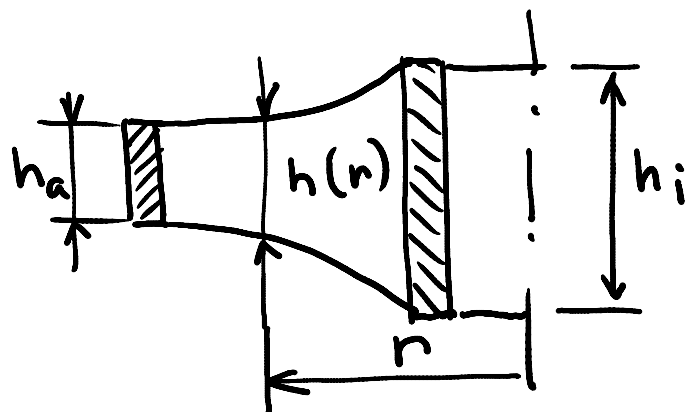
$$\tau_{max} = \frac{F}{A}$$

$$\eta_v = 1$$

ŁOLUTNA STRIŹNA GUMIŹASTA UŁMET



KĄŁO NĄJ SE SPREMINTA UIŐINA UŁMETI, DA BO $\eta_u = 1$?



PRED POSTAVIMO, DA
POŹNAMO h_i, r_i I r_a
I ŐĀEMO h_a I $h(r)$

D.N.